

Physical Damage Simulation on Drone and Wireless Communication Devices by Space Weather Hazard



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Abstract

Drones are widely used for industrial purposes as well as for hobbies, and users are increasing rapidly every year. In this study, we tested the effect on the magnetic sensor in the drone by the Space Weather event. Firstly, we build the magnetic field generator capable of simulating the earth magnetic field while we observe the flight status of the drone as controlling the intensity of the magnetic field. When the geomagnetic disturbance alarm level is G5, the change of magnetic field in Icheon(Geomagnetic Latitude 28°N) in Korea is more than 300nT, so we found that it does not have significant effect on drone. Also, when the magnetic field intensity is more than 51µT, the magnetic sensor have become abnormal and regardless of the amount of change, the magnetic sensor has become abnormal. Nextly, the effect of solar radiation on Wifi frequency band is tested. We give change to noise intensity to test the Wifi reception intensity and quality while the solar propagation noise was calculated simultaneously. Although there was little change in Wifi reception intensity in accordance with the intensity of noise, the quality was gradually decreased, and the solar propagation at the time of rapid decline was calculated to be more than 300 million SFU.

Drone Test

- Purpose
 - > Flight status was observed when magnetic sensor in the drone was effected by geomagnetic change due to solar storm
- Range
 - > Build magnetic field generator to imitate geomagnetic storm and check drone status as we give change geomagnetic field
- Test composition
 - Magnetic field generating device
 - Electromagnet(24V, 0.26A, 1.796kg/ea)
 - Frame : Duralumin Profile, Standard HFS8 Series
 - ✓ Electromagnet fixtures: Duralumin 6061 plate, T12, black aluminate treatment
 - > Power Supply: MK3305P(programmable DC power supply), 30V 5A * 2, 5V 3A *1
 - Drone : Mavic Air
 - Flight Place: Daejeon, Korea(36° 19' 60" N)
- Test contents



Test environment 1

	Test	result	and	conc	usion
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Case 1	Case 2
 Compass Errors when the Magnetic Field intensity is over 51µT(28V) 	 Instantly intensity of magnetic field becomes over 52µT(30V)
Error occurred in the intensity of normal operation over 51μ T(28V)	Compass error occurs
> Returns to normal below approx. 45μ T(13V)	

 \Rightarrow Absolute value of magnetic field

- \checkmark Average intensity of magnetic field in Korea is 40 μ T
- \checkmark As a result, compass error occurs in certain value of intensity(Approx. 51 μ T)
- \Rightarrow Magnetic field variation
 - \checkmark Error occurred in the change of 8 μ T assuming dramatic change of magnetic field

Case 1	Case 2		
Regular change in Magnetic field	Sudden change in Magnetic field		
The voltage is increased at 5			
second intervals of 10 ~ 30 V	Increased Voltage upto 30V		
(total variation 8µT) and then	Turned off after 1 min		
it decreases	Observation on the Drone		



Test environment 2

- \checkmark Normal operation in weak magnetic field intensity in the change of 200 ~ 500 nT (G4 ~ G5 stage)
- \Rightarrow Others
 - \checkmark The magnetic sensor of the drone does not affect the flight due to the multi-calibration device, but there is a risk of the drone loss due to the loss of direction by compass error
 - There is a risk of sensor damage when the sensor repeatedly exposed to strong magnetic field (Requesting sensor correction per test)

Wifi Test

Observation on the Drone

- Purpose
 - > Test for WiFi reception signal strength and quality by Solar Propagation Change
- Range
 - > The wireless router in 2.4GHz band generates a noise signal of 100MHz and transmits it through an antenna to increase the noise intensity, and observes the reception intensity and quality salvage

Test Composition

- > Noise Signal Generator, N5182A MAG vector signal Generator
- Frequency: 100MHz
- Signal Amp.: ZHL-4W-422+(High Power Amplifier 500hm 4W 500 to 4200MHz (Minicircuits))
- Signal Amplifier Output strength: +34dbm
- Antenna: 2.4GHz Yagi(VSWR 1.5 Gain 16dBi)
- Wired and Wireless Router(Wifi device): ipTIME N104R(Frequency 2.4GHz, transmit Power 16dBm ±2dB)
- Cell Phone: Samsung Galaxy S9
- Test Contents
 - Connecting 2.4GHz Wifi Devices
 - Connecting Noise Signal Generator with Signal Amp.
 - Signal Generation with various different Signal
 - Signal Transmission through Amp. setting Antenna towards router
 - Measuring Wifi signal strength, cell phone upload and download

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	Signal	WiFi signal level (Phone)(dBm)	wifi Speed (Mbps)	Cell phone upload SPD. (Mbps)	Cell phone Download SPD. (Mbps)	Delay Time (ms)	Damage Percentage (%)	
	-59.59	-32	72	28.23	28.8	76.6	1.7	
	-54.59	-32	65	32.94	33.82	161.3	3.3	
	-49.59	-31	72	25.88	33.34	426.5	7.5	
	-44.59	-31	65	33.36	32.46	407.2	6.8	
	-39.59	-31	72	4.86	10.4	279.4	4.2	
i de la	-34.59	-32	57	4.69	10.34	1421.3	5.1	
	-29.59	-31	43	0.6	0.63	488.9	5.7	
0	-24.59	-31	39	0.55	1.12	741	2.1	
<u> </u>	-19.59	-32	43	43 NA (Incomprehensible) / Disconnected				
	-14.59	-31	43	43 NA (Incomprehensible) / Disconnected				
y -9.59 -32 43				NA (I	A (Incomprehensible) / Disconnected			
	Default	-30	65	18.09	23.47	78.8ms	9.70%	
	Signal	SFU, B=100MHz	-10		\Rightarrow Wifi Reception	n signal	strength in	
	-59.59	3.45E+07	(Hgp - 20 -		correspondence v	vith Noise sign	al	
	-54.59	1.09E+08	-3030		✓ Signal strength	for the Wifi red	ception is almost	
	-49.59	3.45E+08	-40 - ULI Si Charles		A MARKEN BA	he noise signal stre		
er [-44.59	1.09E+09	≥ -50 - -		\Rightarrow The quality of re			
	-39.59	3.45E+09	-60 +60	50 -40 -30 -20 -10 Noise level (dBm)	and the second s		according to	
ie.	-34.59	1.09E+10	40		noise signal			
	-29.59	3.45E+10	th (Wbps)		✓ Upload and E		is dramatically	
	-24.59	1.09E+11	Received signal quality (Mbps) 15 10 10		decreased under		and the second second	
	-19.59	3.45E+11	pa 15 Neo- 2009 10		 No Internet Conn 	ection under -19d	Bm	
	-14.59	1.09E+12	5		\Rightarrow No change in V	ViFi reception	strength but	
36	-9.59	3.45E+12	0	50 -40 -30 -20 -10 Noise level (dBm)	signal quality drop	IC IIII		

Spd. By Noise signal strength

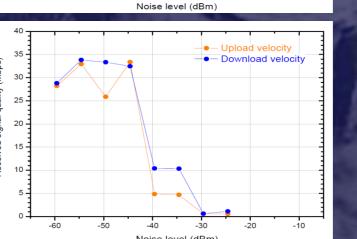
> Solar Flux Unit Calculation corresponding Noise signal strength

 $\checkmark P_R = \frac{1}{2} G \frac{\lambda^2}{4\pi} F$ $\checkmark kTB = \frac{1}{2}GB\frac{\lambda^2}{4\pi}F_{sfu}10^{-22}$

 $\checkmark P_R$: Receiver Power

- ✓ G: Antenna Gain
- $\checkmark k$: Boltzmann constant
- T: Ambient Temperature, 273K

F_{sfu}: SFU



- \Rightarrow Over 3.45x10⁹ SFU, it causes Wifi quality error

Conclusions

• Two kinds of test related to R(Radio Blackout)-value and G(Geomagnetic Storm)-value among Space Weather Condition Components • As a test result, in the mid-latitude region like Korea, there was no significant effect on drone magnetic sensors according to the change of magnetic field strength, but if the calibration is not performed during the continuous magnetic field exposure, the magnetic sensor may be misled In high-level magnetic field 51µT(28V), it was drone flight is difficult while in the area where magnetic field is relatively weak, there is no disturbance in the

- drone magnetic sensor even if the magnetic field strength equivalent of G5
- Wifi signal will not be significantly changed by different noise signal but will be influence by reception signal quality
- As a result of calculating the SFU corresponding to the noise signal, the drop in the Wifi will occur over 3.45x10⁹ SFU

*This Work was supported by IITP(Institute for information & communication Technology Promotion) funded by MSIT(Ministry of Science and ICT) (20180014440011001, Prediction of space weather impacts on industry and countermeasure system development)